

Diameter ø58mm Shaft type/Hollow type/Built-in type Incremental Rotary Encoder

■ Features

- Diameter ø58mm flange type
- Suitable for measuring angle, position, revolution, speed, acceleration and distance
- Power supply : 5VDC, 12-24VDC ±5%

■ Applications

- Various tooling machinery, packing machine and general industrial machinery etc.

⚠ Please read "Caution for your safety" in operation manual before using.



■ Ordering information

E58SC	10	-	8000	-	3	-	N	-	24	-	
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Series	Diameter ø58mm	Shaft diameter	Pulse/1Revolution	Output phase	Output	Power supply	Cable
SC: Shaft Clamping	Ext- ernal	10 ø10mm	Refer to resolution	2: A, B 3: A, B, Z(Standard) 4: A, $\bar{A}$, B, $\bar{B}$ 6: A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$	T: Totem pole output N: NPN open collector output V: Voltage output L: Line driver output	5: 5VDC ±5% 24: 12-24VDC ±5%	No mark: Cable type C: Connector cable type (Cable length: 250mm) CR: Axial connector type CS: Radial connector type
SS: Shaft Synchro		6 ø6mm					
H: Hollow	Inner	12 ø12mm					
HB: Hollow Built-in							

※Standard : E58SC10-PULSE-3-N-24-CR

※Customizable model specifications are available.

※Standard cable for shaft/built-in encoder is axial cable type. Standard cable for hollow shaft encoder is radial cable type.

■ Specifications

Item		Diameter ø58mm incremental rotary encoder		
Resolution(P/R)※1		*1, *2, *5, 10, *12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000, 6000, 8000		
Electrical specification	Output phase		A, B, Z phase(Line driver output : A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$ phase)	
	Phase difference of output		Phase difference between A and B : $\frac{T}{4} \pm \frac{T}{8}$ (T=1cycle of A phase)	
	Control output	Totem pole output	• Low - Load current : Max. 30mA, Residual voltage : Max. 0.4VDC • High - Load current : Max. 10mA, Output voltage(Power voltage 5VDC) : Min. (Power voltage-2.0)VDC, Output voltage(Power voltage 12-24VDC) : Min. (Power voltage-3.0)VDC	
		NPN open collector output	Load current : Max. 30mA, Residual voltage : Max. 0.4VDC	
		Voltage output	Load current : Max. 10mA, Residual voltage : Max. 0.4VDC	
		Line driver output	• Low - Load current : Max. 20mA, Residual voltage : Max. 0.5VDC • High - Load current : Max. -20mA, Output voltage(Power voltage 5VDC) : Min. (Power voltage-2.5)VDC, Output voltage(Power voltage 12-24VDC) : Min. (Power voltage-3.0)VDC	
	Response time (Rise/Fall)	Totem pole output	Max. 1μs	• Measuring condition - Cable length : 2m, I sink = 20mA
		NPN open collector output		
		Voltage output		
		Line driver output		
	Max. Response frequency		300kHz	
	Power supply		• 5VDC ±5%(Ripple P-P : Max. 5%) • 2-24VDC ±5%(Ripple P-P : Max. 5%)	
	Current consumption		Max. 80mA(disconnection of the load), Line driver output : Max. 50mA(disconnection of the load)	
	Insulation resistance		Min. 100MΩ(at 500VDC mega for all terminals and case)	
	Dielectric strength		750VAC 50/60Hz for 1 minute(all terminals and case)	
	Connection		Cable type, 250mm connector cable type, Connector type(Axial, Radial)	
Mechanical specification	Starting torque		• SC/SS type : Max. 40gf·cm(0.004N·m) • HB/H type : Max. 90gf·cm(0.009N·m)	
	Moment of inertia		• SC/SS type : Max. 15g·cm ² (1.5×10 ⁻⁶ kg·m ²) • HB/H type : Max. 20g·cm ² (2×10 ⁻⁶ kg·m ²)	
	Shaft loading		• SC/SS type - Radia : Max. 10kg·f, Thrust : Max. 2.5kg·f • HB/H type - Radial : Max. 2kg·f, Thrust : Max. 1kg·f	
	Max. allowable revolution※2		5000rpm	
Vibration		1.5mm amplitude or 300m/s ² at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours		
Shock		Approx. Max. 75G		
Environment	Ambient temperature		-10 to 70°C, storage : -25 to 85°C	
	Ambient humidity		35 to 85%RH, storage : 35 to 90%RH	
Protection		IP50(IEC standard)		
Cable		ø5, 5-wire, Length : 2m, Shield cable(Line driver output : ø5, 8-wire) (AWG24, Core diameter : 0.08mm, Number of cores : 40, Insulator out diameter : ø1)		
Accessory		ø10mm(SC type) / ø6mm(SS type) coupling, Fixing bracket		
Approval		CE (Except Line driver output)		
Unit weight		• SC-CS/CR type : Approx. 230g, SS-CS/CR type : Approx. 205g, HB-CS/CR type : Approx. 200g • SC type : Approx. 310g, SS type : Approx. 285g, HB type : Approx. 270g, H type : Approx. 270g		

※1: 1, 2, 5, 12 P/R output A and B phase only.(But Line driver output : A, $\bar{A}$, B, $\bar{B}$ phase) [In case of hollow shaft type, 6000, 8000 P/R excluded]

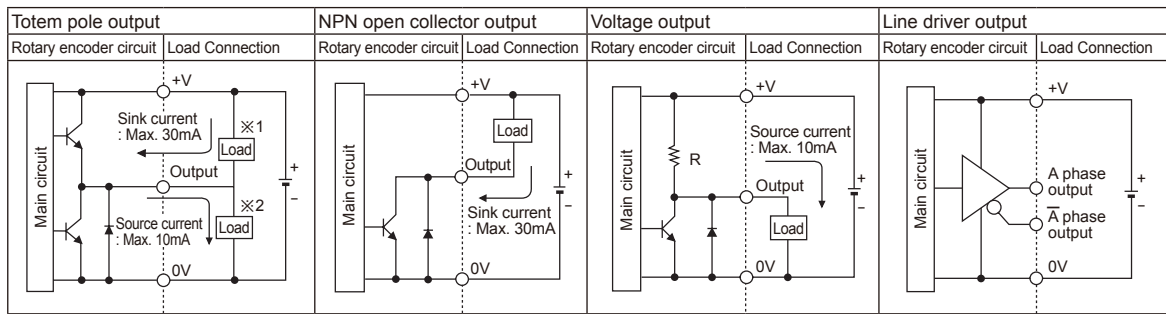
※2: Make sure that. Max response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

[Max. response revolution(rpm)] = $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$

※Environment resistance is rated at no freezing or condensation.

Incremental ø58mm Shaft/Hollow Shaft/Built-in type

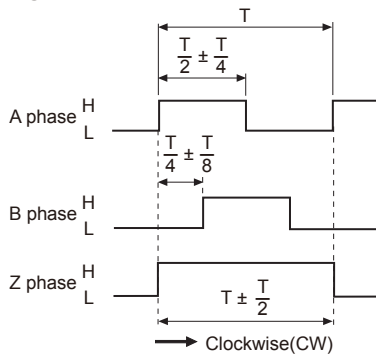
■ Control output diagram



- Totem pole output type can be used for NPN open collector output type(※1) or Voltage output type(※2).
- All output circuits of A, B, Z phase are the same. (Line driver output is A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$)

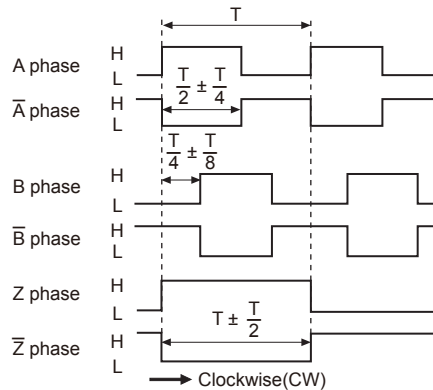
■ Output waveform

- Totem pole output / NPN open collector output / Voltage output



※CW : Right turn as from the shaft

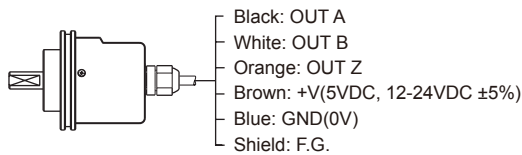
- Line driver output



■ Connections

◎ Cable type

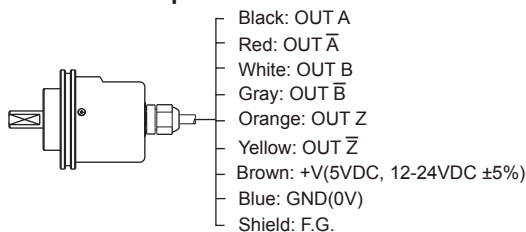
- Totem pole output / NPN open collector output / Voltage output



※Unused wires must be insulated.

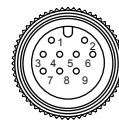
※The metal and shield cable of encoder should be grounded(F.G.)

- Line driver output



◎ Connector cable type / Connector type

- Totem pole output / NPN open collector output / Voltage output
- Line driver output



Totem pole output/ NPN open collector output/ Voltage output			Line driver output		
Pin No	Function	Cable color	Pin No	Function	Cable color
①	OUT A	Black	①	OUT A	Black
②	OUT B	White	②	OUT $\bar{A}$	Red
③	OUT Z	Orange	③	+V	Brown
④	+V	Brown	④	GND	Blue
⑤	GND	Blue	⑤	OUT B	White
⑥	F.G.	Shield	⑥	OUT $\bar{B}$	Gray
—			⑦	OUT Z	Orange
			⑧	OUT $\bar{Z}$	Yellow
			⑨	F.G.	Shield

※F.G.(Field Ground) : It should be grounded separately.

(A)
Photo
electric
sensor

(B)
Fiber
optic
sensor

(C)
Door/Area
sensor

(D)
Proximity
sensor

(E)
Pressure
sensor

(F)
Rotary
encoder

(G)
Connector/
Socket

(H)
Temp.
controller

(I)
SSR/
Power
controller

(J)
Counter

(K)
Timer

(L)
Panel
meter

(M)
Tacho/
Speed/
Pulse
meter

(N)
Display
unit

(O)
Sensor
controller

(P)
Switching
mode power
supply

(Q)
Stepper
motor&
Driver&Controller

(R)
Graphic/
Logic
panel

(S)
Field
network
device

(T)
Software

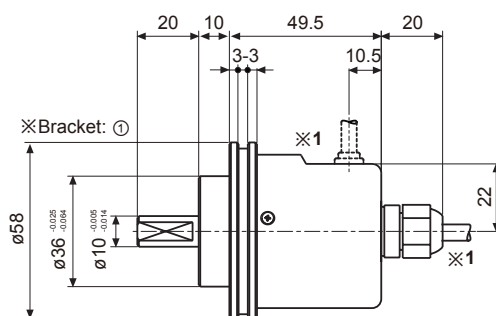
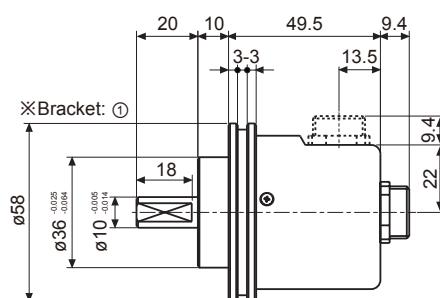
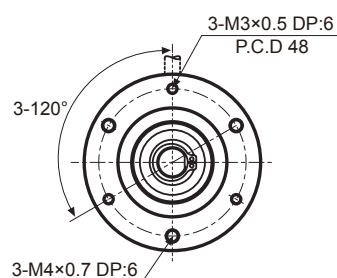
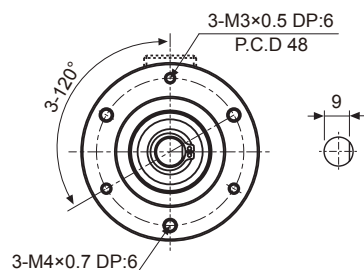
(U)
Other

E58 Series

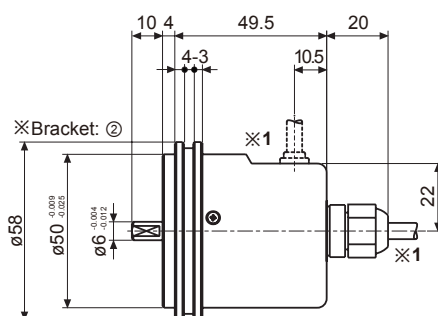
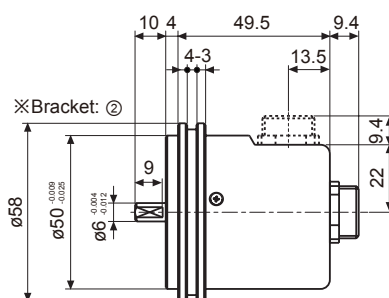
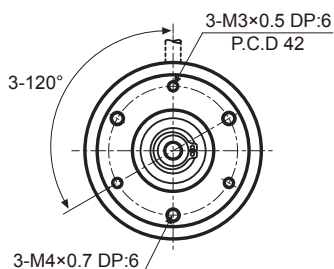
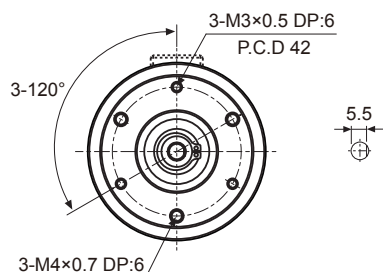
■ Dimensions

◎ **Shaft clamping type**

(unit: mm)

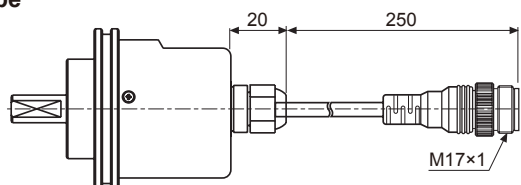


© **Shaft synchro type**



※1:	Cable for cable type
	ø5, 5-wire(Line driver output : 8-wire), Length : 2000, Shield cable

- **Cable connector type**

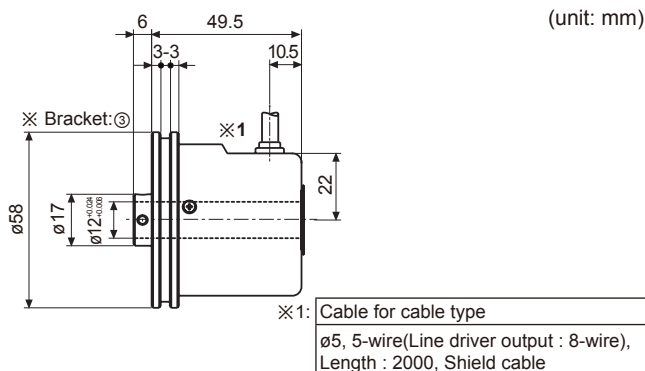
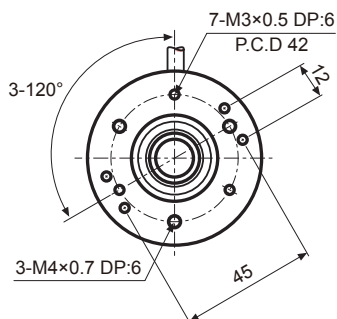


※Connector cable is customizable and refer to the G-10 for specifications.

Incremental ø58mm Shaft/Hollow Shaft/Built-in type

■ Dimensions

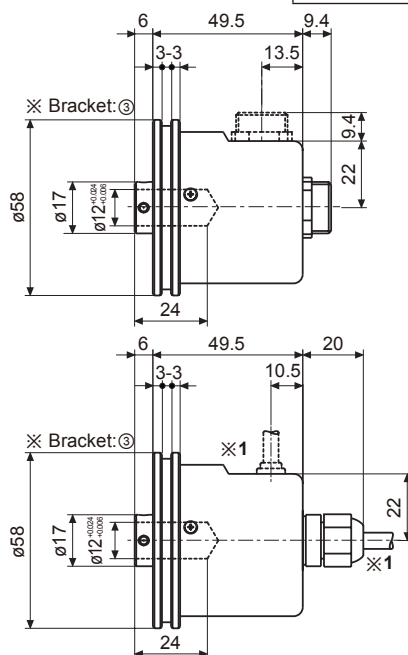
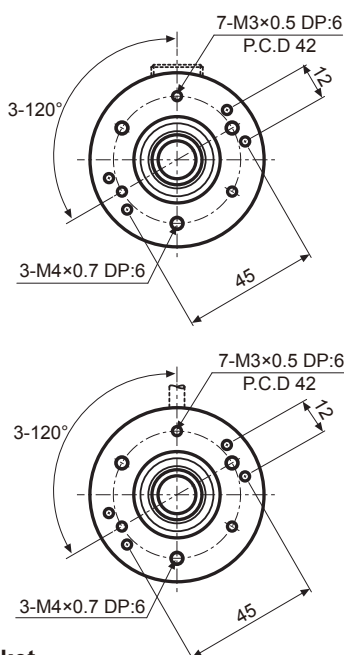
© **Hollow type**



(unit: mm)

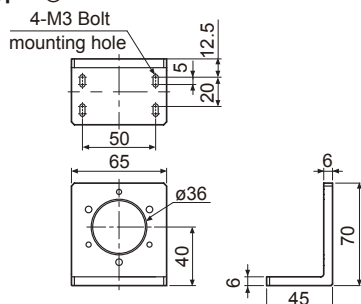
※1:	Cable for cable type
	ø5, 5-wire(Line driver output : 8-wire), Length : 2000, Shield cable

© **Hollow built-in type**

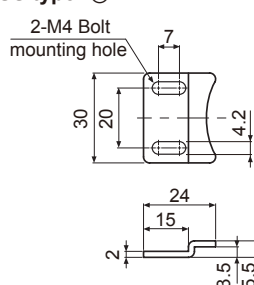


- **Bracket**

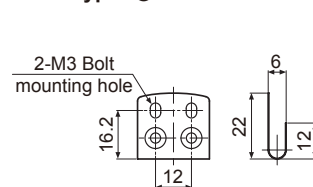
※SC type: ①



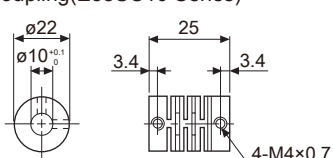
※SS type: ②



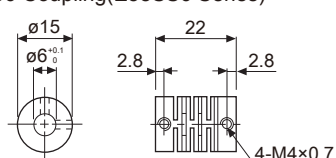
※HB/H type: ③



- ø10 Coupling(E58SC10 Series)



- ø6 Coupling(E58SS6 Series)



- Parallel misalignment: Max. 0.25mm
- Angular misalignment: Max. 5°
- End-play: Max. 0.2mm

- ※ For parallel misalignment, angular misalignment, end-play terms, refer to the F-77 page.
- ※ For flexible coupling(ERB Series) information, refer to the F-70 page.

(A)	Photo electric sensor
(B)	Fiber optic sensor
(C)	Door/Area sensor
(D)	Proximity sensor
(E)	Pressure sensor
(F)	Rotary encoder
(G)	Connector/Socket
(H)	Temp. controller
(I)	SSR/Power controller
(J)	Counter
(K)	Timer
(L)	Panel meter
(M)	Tacho/Speed/ Pulse meter
(N)	Display unit
(O)	Sensor controller
(P)	Switching mode power supply
(Q)	Stepper motor& Driver&Controller
(R)	Graphic/Logic panel
(S)	Field network device
(T)	Software
(U)	Other